

Dual Setting Type

Dual setting type, High accuracy temperature controller

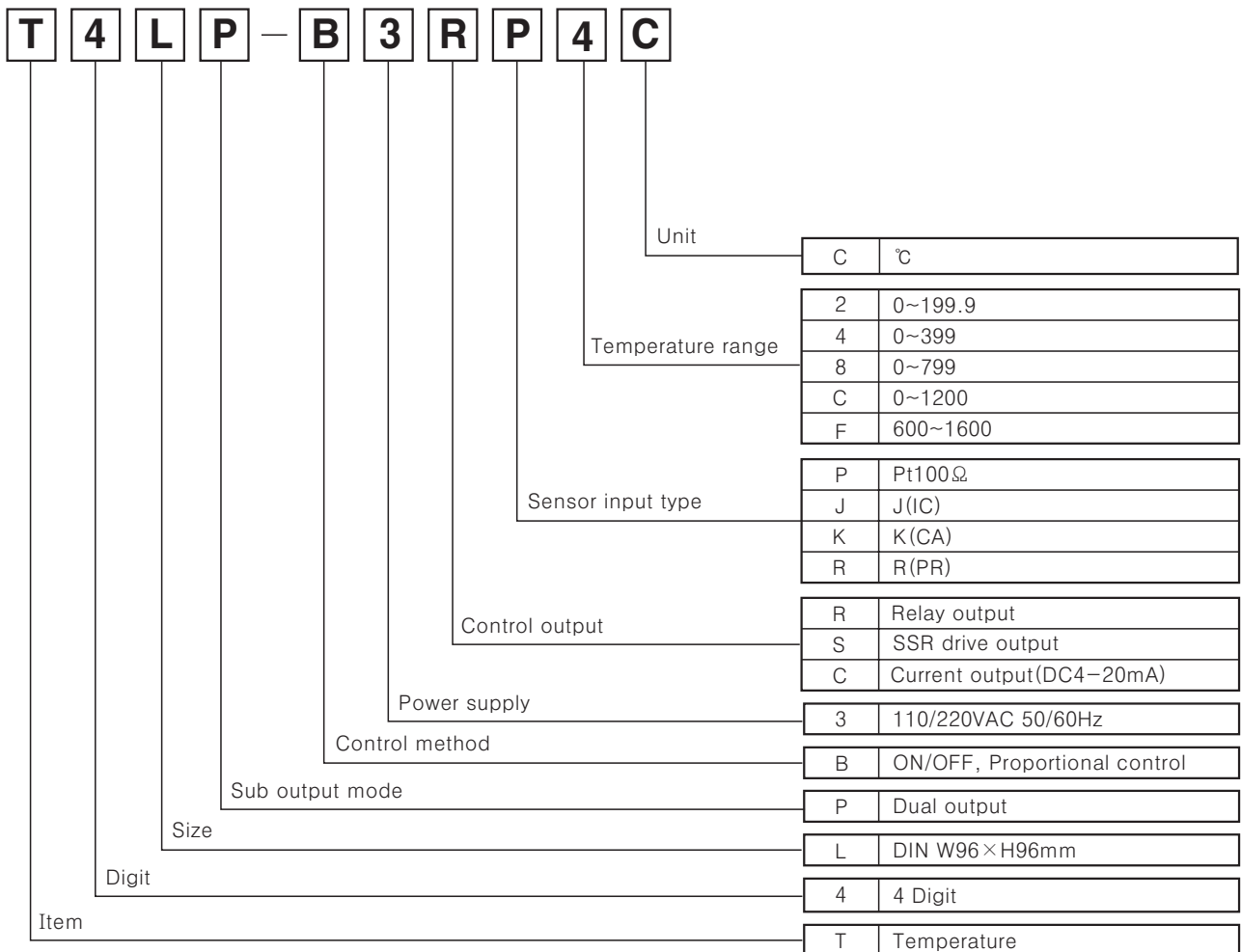
■ Features

- Dual setting type
- High accuracy measuring function : $\pm 0.5\%$
- Control heater and cooler at once
- Use dual setting type of temperature when executing low temperature or precision control. In dual setting control type, the single output is operated as reverse, it is used for heater control. The dual output is used to control the operation of cooler normally. The dual output is also used for an alarm.



⚠ Please read "Caution for your safety" in operation manual before using.

■ Ordering information



※ See C-63 about sensor temperature range for selection.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

T4LP

Temperature range for each sensor

Model		T4LP			
Sensor input type	°C	Thermocouples			RTD
		J(IC)	K(CA)	R(PR)	Pt100Ω
Standard scale range	1600			1600°C	
	1200				
	1000				
	800				
	600				
	400	399°C		600°C	
	200		399°C		
	100		799°C		
	0				
	-100				
			1200°C		
					199.9°C
					399°C

※ In case, the sensor is R(PR) type, it is not available to indicate the temperature and control correctly.

Specifications

Model		T4LP
Power supply		110/220VAC 50/60Hz
Allowable voltage range		90 ~ 110% of rated voltage
Power consumption		3VA
Display method		7 Segment LED Display
Character size		W9.5×H14.2mm
Display accuracy		F · S ± 0.5% rdg ± 1digit
Setting type		Digital switch setting
Setting accuracy		F · S ± 0.5%
Sensor input		Thermocouples : K(CA), J(IC), R(PR) / RTD : Pt100Ω
Input line resistance		Thermocouples : Max. 100Ω, RTD : Max. 5Ω per a wire
Control method	ON/OFF	Hysteresis F · S 0.2 ~ 3%
	Proportional	Proportional band : F · S 1 ~ 10%, Period : 20sec. fixed
RESET adjuster range		F · S ± 3% (Only for control deviation)
Control output		<ul style="list-style-type: none"> Relay output : 1st out : 250VAC 3A 1c, 2nd out : 250VAC 2A 1c SSR drive output : 24VDC ± 3V 20mA max. Current output : DC4~20mA Load 600Ω max.
Self-diagnosis		Includes burn out function
Insulation resistance		Min. 100MΩ (at 500VDC mega)
Dielectric strength		2000VAC 50/60Hz for 1 minute
Noise strength		± 2kV the square wave noise (pulse width: 1μs) by the noise simulator
Vibration	Mechanical	0.75mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 1 hour
	Malfunction	0.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes
Shock	Mechanical	300m/s ² (Approx. 30G) 3 times at X, Y, Z direction
	Malfunction	100m/s ² (Approx. 10G) 3 times at X, Y, Z direction
Relay life cycle	Mechanical	Min. 10,000,000 times
	Electrical	Min. 100,000 times (250VAC 3A at resistive load)
Ambient temperature		-10 ~ +50°C (at non-freezing status)
Storage temperature		-20 ~ +60°C (at non-freezing status)
Ambient humidity		35 ~ 85%RH
Unit weight		Approx. 487g

※ (Note) F.S is same with sensor measuring temperature range.

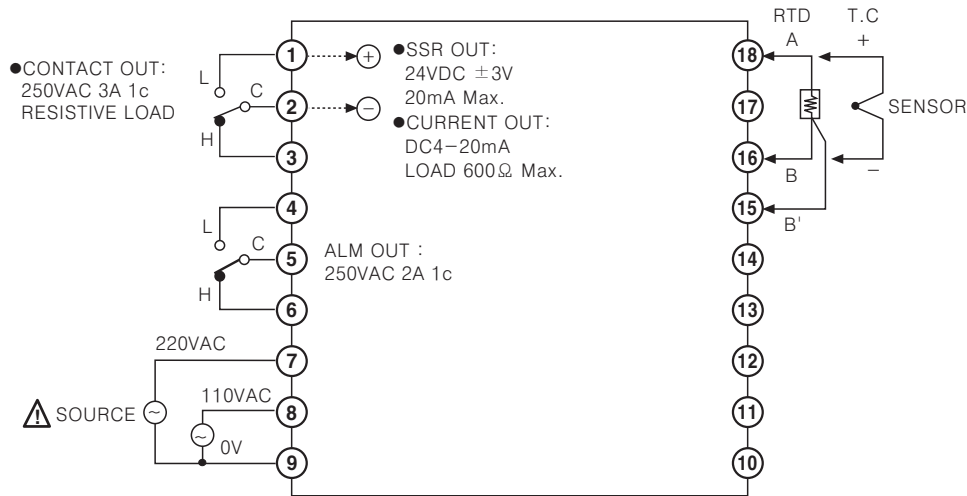
Ex) In case of using temperature is from -99.9 ~ 199.9°C, Full scale is 299.8.

Dual Setting Type

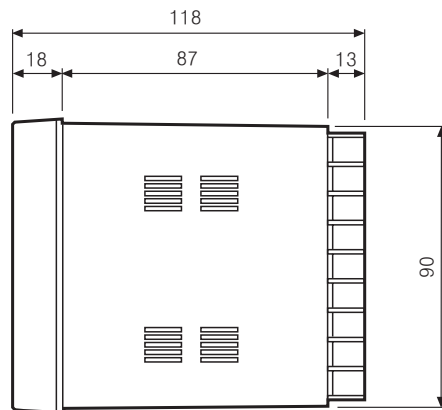
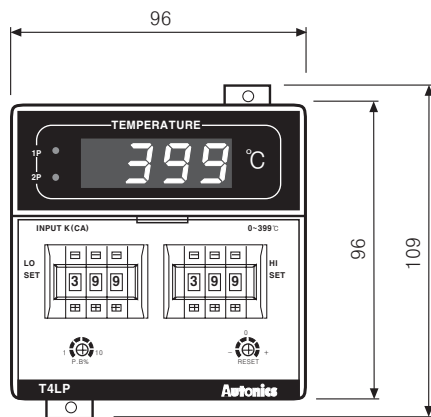
Connections

※RTD(Resistance Temperature Detector) : Pt 100Ω(3-wire type)

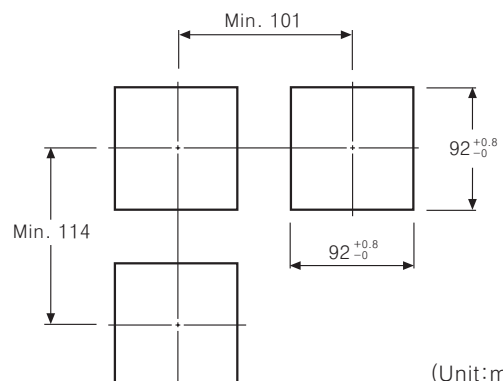
※Thermocouple : K, J, R



Dimensions



●Panel cut-out



(Unit:mm)

(A)
Counter

(B)
Timer

(C)
Temp.
controller

(D)
Power
controller

(E)
Panel
meter

(F)
Tacho/
Speed/
Pulse
meter

(G)
Display
unit

(H)
Sensor
controller

(I)
Switching
power
supply

(J)
Proximity
sensor

(K)
Photo
electric
sensor

(L)
Pressure
sensor

(M)
Rotary
encoder

(N)
Stepping
motor &
Driver &
Controller

(O)
Graphic
panel

(P)
Field
network
device

(Q)
Production
stoppage
models &
replacement

■ Proper usage

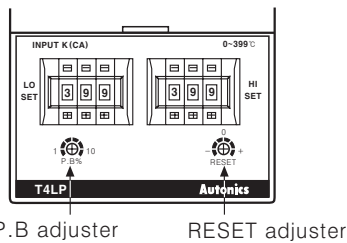
◎ Operation

This controller has two outputs operated separately. In other words, it is able to set the values separately. Front Low Set runs with reverse operation as other common controllers and High Set runs by normal operation. It is able to control heater and cooler.



※ Terminal block ①, ②, ③ are for Low set output and terminal block ④, ⑤, ⑥ are for High set output.

◎ Using front adjuster



● P.B adjuster

In case of ON/OFF control, set variable $F \cdot S$ 0.2~3% of hysteresis, and in case of proportional control, set variable $F \cdot S$ 1~10% of hysteresis.

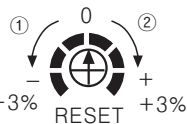
● RESET adjuster

It corrects offset can be occurred by proportional control and has $F \cdot S \pm 3\%$ of adjustable range.

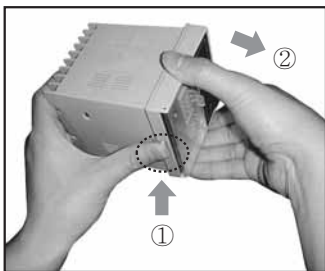
Do not operate the adjuster when it is used as ON/OFF control.

① Turn left when offset value is higher than set value. (Direction ①)

② Turn right when offset value is lower than set value. (Direction ②)



◎ Case detachment

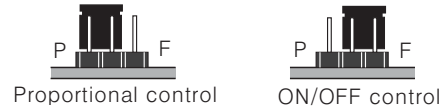


Pressing the front guide of Lock toward ① and squeeze and pull toward ②, it is detached.

◎ How to select ON/OFF or proportional by plug pin

Factory specification is proportional control.

When using ON/OFF control, transfer the switch of control method from P to F after detaching the case from its body.



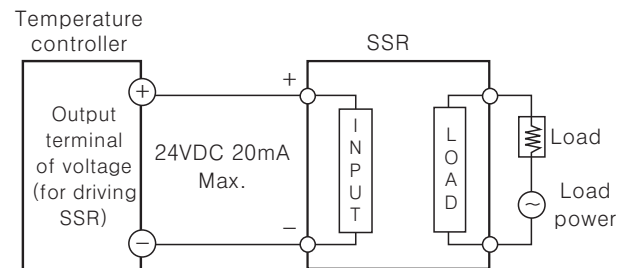
◎ Normal/Reverse operation

Reverse operation executes to output ON when process value is lower than setting value, and it is used for heating.

Normal operation is executed conversely and used for cooling. (This item runs as a reverse operation.)

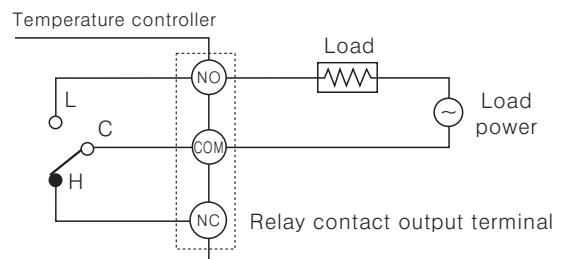
◎ Application of temperature controller and load connection

● SSR output



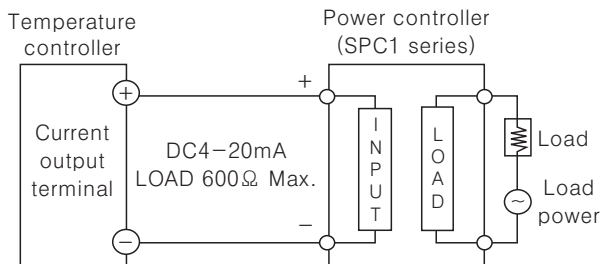
※ When using voltage (for driving SSR) in the other purposes, do not exceed the range of the rated current.

● Relay output



Output	Relay contact capacity
1st OUT	250VAC 2A
2nd OUT	250VAC 3A

● Current output



※ The current value of DC4~20mA is available at lower than 600Ω of resistive load.